Symmetry perception by poultry chicks and its implications for three-dimensional object recognition

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Bilateral symmetry is visually salient to diverse animals including birds, but whereas experimental studies typically use bilaterally symmetrical two-dimensional patterns that are viewed approximately fronto-parallel; in nature, animals observe three-dimensional objects from all angles. Many animals and plant structures have a plane of bilateral symmetry. Here, we first (experiment I) give evidence that young poultry chicks readily generalize bilateral symmetry as a feature of two-dimensional patterns in fronto-parallel view. We then test the ability of chicks to recognize symmetry in images that would be produced by the transformed view produced by a 40° horizontal combined with a 20° vertical rotation of a pattern on a spherical surface. Experiment II gives evidence that chicks trained to distinguish symmetrical from asymmetrical patterns treat rotated views of symmetrical ‘objects’ as symmetrical. Experiment III gives evidence that chicks trained to discriminate rotated views of symmetrical ‘objects’ from asymmetrical patterns generalize to novel symmetrical objects either in fronto-parallel or rotated view. These findings emphasize the importance of bilateral symmetry for three-dimensional object recognition and raise questions about the underlying mechanisms of symmetry perception.

Keywords: symmetry; vision; object recognition; domestic chick; categorization

1. INTRODUCTION

Visual symmetry is important in nature: most animals are bilaterally symmetrical and symmetry is treated as a desirable characteristic of potential mates [1–3]. Also, the assumption that an object has a plane of symmetry can be used to compute its three-dimensional shape from the two-dimensional optical image [4,5]. Animals are sensitive to bilateral symmetry, and often prefer symmetrical patterns [6–10]. For instance, pigeons (Columba livia) and bees can learn to classify bilaterally symmetrical to be distinct from asymmetrical and rotationally symmetrical patterns [11–13].

The ethological literature has two main accounts of symmetry preference in animals. One account argues that symmetry gives information about the signaller’s quality, and that symmetry preferences evolved to identify high-quality food or mates [1–3,14]. The alternative ‘aesthetic’ account argues that visual mechanisms of image segregation and object recognition are inherently sensitive to symmetry [15–17]. Support for this latter view comes from evidence that symmetry is an organizational factor in perceptual grouping that facilitates figure-ground segregation [18,19], and has a role in object recognition [5,20,21]. Similarly, symmetry preference could arise from generalization from multiple views of a given object, and it allows detection and recognition of objects from novel viewpoints [15,16,22,23]. One might expect symmetry detection to involve long-range comparisons of potentially conjugate points in the image, but this process is computationally costly and it has been proposed that symmetry is a local feature comparable with edges and lines [17,24–26].

A limitation of nearly all theoretical and experimental studies of symmetry perception is that they consider two-dimensional bilateral symmetry in fronto-parallel view, normally with a vertical axis of symmetry [26]. Self-evidently, bilaterally symmetrical patterns and objects do not normally produce a symmetrical retinal image. Two main types of transformations are possible: skewed projections caused by viewing a symmetrical two-dimensional pattern out of the fronto-parallel plane [27], and the more complex transformations produced by rotating a three-dimensional symmetrical object [5]. It is relevant here that the three-dimensional structure can often be inferred from a two-dimensional view, given a prior assumption that an object is symmetrical [4,5]. To our knowledge, study of perception of transformations of bilaterally symmetrical two-dimensional patterns and three-dimensional objects is limited to human subjects; these confirm that humans identify bilateral symmetry in skewed projections of two-dimensional patterns [28–32].

Clearly, consideration of how non-human animals classify asymmetrical two-dimensional stimuli that are (potentially) generated by symmetrical three-dimensional objects is relevant to understanding symmetry in natural vision and visual signalling, while behavioural capabilities can have implications for the underlying neural mechanisms. The present study investigates how poultry chicks categorize symmetry as a visual feature [13], and then how...
they generalize from two-dimensional retinal projections of three-dimensional symmetrical objects. Experiment I shows that young chicks generalize bilateral symmetry with two-dimensional fronto-parallel patterns. Experiments II and III go on to look at simulation of rotations of three-dimensional objects, by testing generalization between symmetrical training patterns and stimuli that simulate the transformation produced by combining a 40° horizontal with a 20° vertical rotation of a pattern on a spherical surface.

2. METHODS
(a) Subjects
For experiment I, subjects were 88 male domestic chicks (Gallus gallus; Strain ‘Bovans Goldline’) from a commercial hatchery (Joice & Hill, Peterborough, UK). For experiments II and III, subjects were, respectively, 88 and 90 male chicks (White Leghorn, Hybro strain) from a commercial hatchery (Agricola Berica, Montegalda, Vicenza, Italy).

(b) Exposure stimuli and apparatus
The exposure apparatus was a standard metal home cage (40 × 28 × 30 cm) with two screens (6 × 9 cm) located in two adjacent corners (figure 1a). One of the screens had a symmetrical pattern (2.5 × 4 cm) printed on both sides of it, the other an asymmetrical pattern. A food dish was hidden behind each screen; one dish was empty and the other contained food (chicken starter feed). For each pair of chicks, the symmetrical stimulus was always associated with either the full or the empty dish. A set of three pairs of shapes was available, so that each pair of chicks could be exposed alternately to two of them and subsequently tested with the third, and previously unseen, one.

For experiments I and II, the exposure stimuli were two pairs of symmetrical/asymmetrical shapes consistent with a fronto-parallel view (figure 2a); for experiment III, the exposure stimuli were a transformed version of the same symmetrical and asymmetrical shapes, consistent with rotation of three-dimensional objects (figure 2b; appendix A gives the algorithm used for generating such stimuli).

(c) Test stimuli and apparatus
The test stimuli consisted of the symmetrical shape and the asymmetrical shape that the pair of chicks had not previously seen. The test apparatus (figure 1b) was a white-plywood runway (75 × 20 × 30 cm), subdivided virtually into a central area (15 cm long) and two side areas (each one 30 cm long), with the test stimuli placed at the two ends, 22.5 cm from the centre.

(d) Procedure
On their arrival at the laboratory (on day 1 of life), chicks were placed in pairs in the exposure apparatus (see above). Two screens, each hiding one of two food dishes, were placed in two corners of the cage. Depending on the pair of chicks, the symmetrical stimulus was associated with either the full or the empty dish. In experiment I, the exposure period ran from the afternoon of day 1 until the morning of day 4. For each pair of chicks, two pairs of stimuli (each pair consisting of one symmetrical and one asymmetrical stimulus) were used during the exposure period, the pair of screens being alternated every 2 h (i.e. two times for the afternoon of day 1 post-hatching and the morning of day 4, four times a day for days 2 and 3, with food being freely available in a standard dish overnight). Which two pairs of stimuli (out of the three pairs) and their initial location in the cage were balanced across subjects. The positions of the two stimuli within the cage were swapped regularly for each pair of chicks. Experiments II and III followed the same training protocol, saving that exposure to the training stimuli continued overnight on days 2 and 3 (exposure stimuli being different for the two nights).

On day 4, in the early afternoon, each pair of chicks was taken from its cage and placed in the central area of the test apparatus (figure 1b). Chicks were tested in pairs because the presence of a companion minimizes the typical freezing response to a novel environment and facilitates exploratory and feeding behaviours [33]. The symmetrical and asymmetrical shapes not seen before by the chicks were placed at opposite ends of the runway, each printed on a screen hiding an empty food dish.
The chicks were observed for six consecutive minutes. The behaviour of individual chicks in a pair is not independent because of social facilitation of exploratory responses. Therefore, for the data analysis, each pair of chicks was treated as a single unit.

If both chicks remained in the mid-compartment or expressed opposite choices (i.e. one of the chicks chose one of the end-side compartments meanwhile the other chick chose the other end-side compartment), this was deemed to indicate no preference. If at least one of the chicks went into an end-side compartment, this was regarded as a preference for the object placed at that end of the runway.

A computer-driven event recorder allowed the experimenter to score the time (seconds) spent by the pair of chicks in each of the three compartments. The proportion of time spent near the stimulus belonging to the same category which had been associated with food during the exposure phase was computed as:

\[
\text{time (s) spent near the 'reinforced' category} \div \text{time (s) spent in both side areas} \times 100.
\]

The index values ranged from 0 (full choice for the ‘not-reinforced’ category) to 100 (full choice for the ‘reinforced’ category).

Data were analysed with repeated-measures ANOVA; departures from random choice were estimated by one-sample (two-tailed) t-tests (SPSS statistical package).

3. RESULTS

(a) Experiment I

This experiment examined how chicks trained to discriminate bilaterally symmetrical from asymmetrical patterns generalize to novel asymmetrical patterns according to whether or not they are consistent with being rotated views of bilaterally symmetrical three-dimensional objects. Twenty-six pairs of chicks had food associated with the symmetrical shapes (i.e. reinforced category: symmetry), and 18 pairs had food associated with the asymmetrical shapes (i.e. reinforced category: asymmetry). The test stimuli consisted of a rotated view of the symmetrical and asymmetrical shapes never experienced before (figure 2b).

A repeated-measures ANOVA with reinforced category (symmetry versus asymmetry) as the between-subject factor, and time (from 1 to 6 min) as within-subject factor did not reveal any significant effect or interaction (time: \(F_{5,210} = 1.644, p = 0.150\); reinforced category: \(F_{1,42} = 0.100, p = 0.733\); time \times\ reinforced category: \(F_{5,210} = 1.353, p = 0.243\)).

Overall, chicks approached and stayed closer to the reinforced stimulus-type significantly more than the unreinforced (mean ± s.e.m. = 59.307 ± 3.635; one-sample t-test: \(t_{43} = 2.560, p = 0.014\); figure 3). Such a preference was above chance in the third and in the sixth minute of the test (third minute: mean ± s.e.m. = 61.673 ± 5.205; one-sample t-test: \(t_{43} = 2.243, p = 0.030\); sixth minute: mean ± s.e.m. = 66.936 ± 5.522; one-sample t-test: \(t_{43} = 3.067, p = 0.004\)); it was not marginally significant on minute four (mean ± s.e.m. = 59.909 ± 5.668; one-sample
stimuli in figure 2; i.e. reinforced category: asymmetry). Chicks were divided into two groups: 25 pairs were tested with the fronto-parallel version of the symmetrical and asymmetrical shapes to which they had not been exposed to previously (i.e. stimuli in figure 2a); 20 pairs of chicks were tested with the distorted version of the symmetrical and asymmetrical shapes never experienced before (stimuli in figure 2b).

A repeated-measures ANOVA with reinforced category (symmetry versus asymmetry) as between-subject factor, type of test stimuli (fronto-parallel versus distorted) and time (from 1 to 6 min) as within-subject factors did not reveal any significant effect or interaction (time: $F_{5,205} = 1.045$, $p = 0.392$; reinforced category: $F_{1,41} = 2.800$, $p = 0.102$; type of test stimuli: $F_{1,41} = 3.016$, $p = 0.090$; reinforced category $\times$ type of test stimuli: $F_{1,41} = 0.707$, $p = 0.792$; time $\times$ reinforced category: $F_{5,205} = 0.994$, $p = 0.449$; time $\times$ type of test stimuli: $F_{5,205} = 1.785$, $p = 0.117$; time $\times$ reinforced category $\times$ type of test stimuli: $F_{5,205} = 0.539$, $p = 0.747$).

Overall, subjects significantly chose to approach and stayed closer to the stimulus-category which was reinforced at training significantly more than to the non-reinforced (mean $\pm$ s.e.m. = 59.024 $\pm$ 4.086; one-sample t-test: $t_{14} = 2.208$, $p = 0.032$; figure 3). Although the effect of the type of test stimuli was not significant at the ANOVA, it is worth noting that the subgroup of chicks tested with the distorted stimuli, in spite of these being more similar to the stimuli employed during training, performed at chance in every one of the 6 min of the test (figure 3). While the subgroup of chicks tested with the non-distorted version of the stimuli performed above chance or nearly so starting from the third minute of the test (third minute: mean $\pm$ s.e.m. = 69.483 $\pm$ 7.583; one-sample t-test: $t_{24} = 2.569$, $p = 0.017$; fourth minute: mean $\pm$ s.e.m. = 65.788 $\pm$ 8.467; one-sample t-test: $t_{24} = 1.865$, $p = 0.074$; fifth minute: mean $\pm$ s.e.m. = 73.178 $\pm$ 8.152; one-sample t-test: $t_{24} = 2.843$, $p = 0.009$; sixth minute: mean $\pm$ s.e.m. = 69.294 $\pm$ 7.846; one-sample t-test: $t_{24} = 2.459$, $p = 0.022$).

4. DISCUSSION

Experiment I demonstrates that 4 day old domestic chicks can learn and generalize symmetry as a visual category. Experiment II gives evidence that chicks trained to discriminate symmetrical from asymmetrical patterns successfully classify rotated views of novel objects according to whether or not they could have been generated by a symmetrical three-dimensional object. To our knowledge, this is the first evidence for such generalization in a non-human species.

Thus, we give evidence that 4 day old chicks can classify objects according to whether or not they have a plane of symmetry. While this observation is relevant to natural behaviour, it is in a sense purely qualitative. In the absence of a specific hypothesis about the mechanism of
symmetry detection, it is difficult to compare the degree of asymmetry in the test stimuli that represent rotated symmetrical objects to the asymmetrical alternatives. More evidence is needed to understand the mechanism that would allow animals to exploit symmetry as a visual cue to identify three-dimensional objects (i.e. mates or food) seen from multiple viewing angles. The fact that chicks generalize the presence of symmetry to novel objects rules out the possibility—suggested for primate face recognition [33–35]—that they recognize objects simply by storing multiple views.

It would be interesting to investigate the ecological value of such symmetry perception. For example, which symmetrical objects (insects, seeds, predators, etc.) are ecologically relevant for each species. This would require quantitative analysis of symmetry in natural objects and experimental stimuli. It would also be interesting to learn how the preference for bilateral symmetry is affected by distortions caused by non-fronto–parallel views. Moreover, in further research, a wide range of experimental stimuli should be used to confirm the results of the present paper.

Finally, the possibility of performing controlled-rearing studies with chicks opens the door to direct investigation of the neural and genetic basis of such symmetry detection mechanism.

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APPENDIX A
Initially, the image \( I(\{x, y\} \in \{0, 1\}) \) is orthogonally projected into the surface of unit sphere parametrized by the Cartesian coordinates \((a, b, c)\). \( r \) is the radius of the unit sphere.

\[
(a, b, c) = \left( \frac{x}{r}, \frac{y}{r}, \sqrt{(r^2 - x^2 - y^2)}/r \right).
\]

The rotation used was chosen so as to preserve the effective orientation of the image. For this reason, the rotation was performed by two consecutive rotations, first around the vertical axis of the image plane and second around the horizontal.

\[
R_x = \begin{pmatrix}
1 & 0 & 0 \\
0 & \cos \theta & -\sin \theta \\
0 & \sin \theta & \cos \theta 
\end{pmatrix}
\]

and

\[
R_y = \begin{pmatrix}
\cos \varphi & 0 & \sin \varphi \\
0 & 1 & 0 \\
\sin \varphi & 0 & \cos \varphi 
\end{pmatrix}.
\]

REFERENCES


